

**GPS and ITS  
APPLICATIONS IN  
EARTHQUAKE STUDIES**

**By**

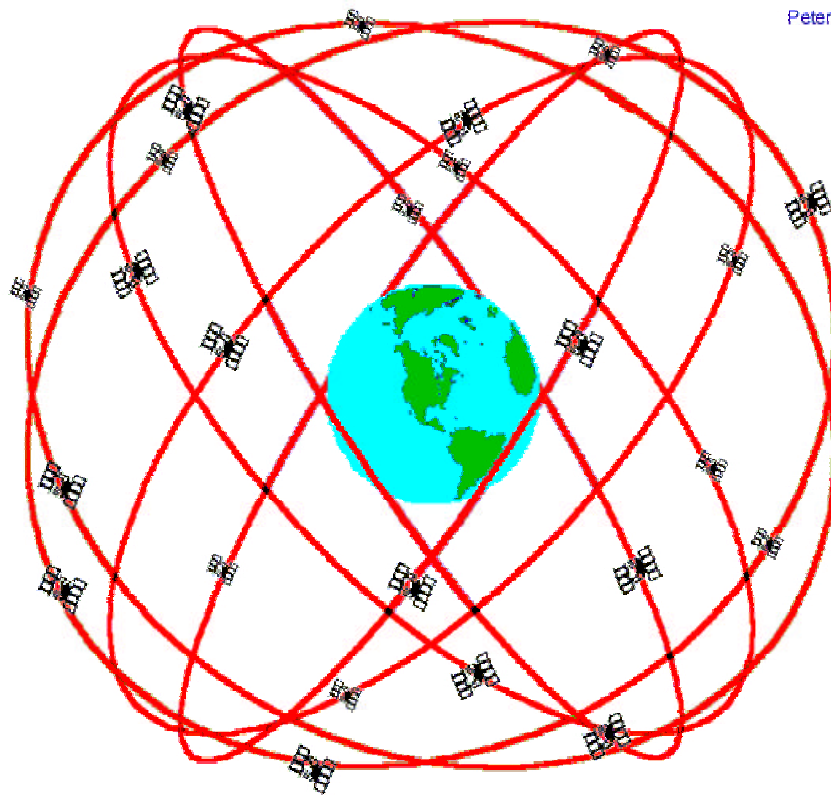
**Dogan AKSARI**

# Global Positioning System

## Introduction

### ERROR SOURCES

### GPS



Peter H. Dana 9/22/98

**GPS Nominal Constellation**  
24 Satellites in 6 Orbital Planes  
4 Satellites in each Plane  
20,200 km Altitudes, 55 Degree Inclination

Presentation Title

Main Topic

First Subtopic

Second Subtopic

Body of Topic

Number of Slide

- GEODETIC METHOD = EDM, VLBI, SLR ..... GPS
- GPS=Economic and Precise
- GPS = HIGH PRECISION, ECONOMIC
- GEOPHYSICS USES GPS TO EXPLAIN
  - Plate Movement and Plate Boundary Deformations
  - Volcanic Deformation
  - Glacial Isostatic Adjustment and Sea Level Change
  - Landslide and Dam Deformations
  - **Earthquake Studies**
    - **Interseismic Deformation**
    - **Coseismic Deformation**
    - **Postseismic Deformation**

- GPS Overview
- Earthquake Studies
  - Interseismic Deformation
  - Coseismic Deformation
  - Postseismic Deformation
- Studying 17 Augustos 1999 Kocaeli Earthquake provided GPS Observations

# Geodesy

# Space Geodesy

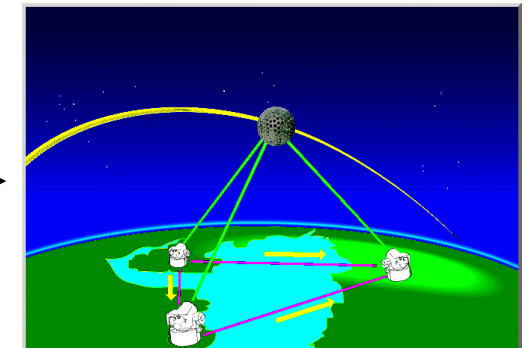
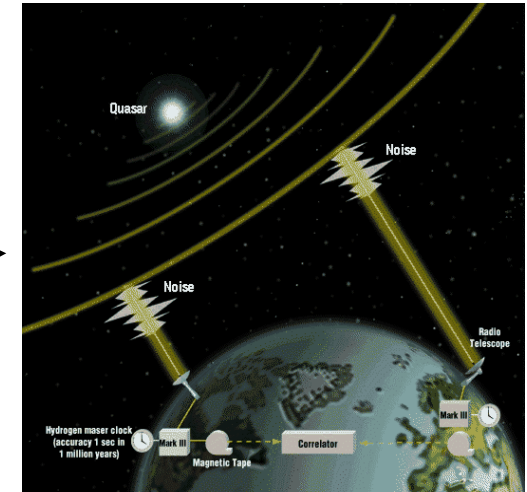
## Geodetic Methods

VLBI (Very Long Baseline Interferometry) \_\_\_\_\_

SLR (Satellite Laser Ranging) \_\_\_\_\_

LLR (Lunar Laser Ranging) \_\_\_\_\_

GPS (Global Positioning System) \_\_\_\_\_



### GPS

- ❖ 1957 Launch of first satellite, SPUTNIK by former Soviet Union
- ❖ 1957 TRANSIT system by USA
  - 6 orbit planes, 6 satellites, 1100 km above the earth
- ❖ 1967 ZIKADE system by former USSR
  - 6 orbit planes, 6 satellites, 1100 km above the earth
- ❖ 1974 GPS by USA
- ❖ The GPS became fully operational on December 8, 1993
  - ❖ 6 orbit planes, 24 satellites, 20200 km above the earth
- ❖ The Global Positioning System is based on the US Department of Defense's NAVSTAR Satellites.
- ❖ GPS costs \$12 billion.
- ❖ Error add into satellite signals, called SA (Selective Availability)
- ❖ Military receivers have a description key to remove SA error.
- ❖ SA was totally removed at May 2, 2000.

## ❁ Space Segment

- ❁ Satellites

## ❁ Control Segment

- ❁ Control Stations

  - ❁ Master Control Station

  - ❁ Monitor Stations

  - ❁ Ground Control Stations

- ❁ Antennas

## ❁ User Segment

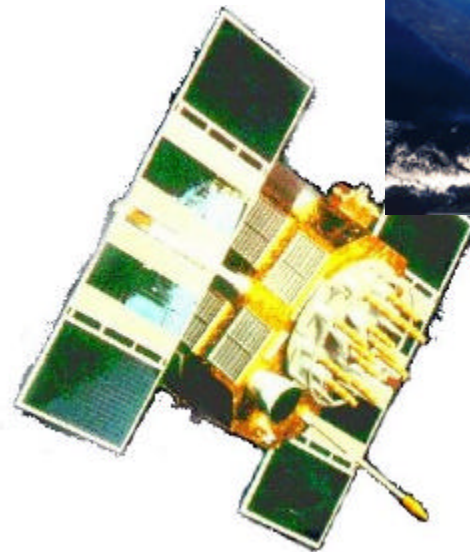
- ❁ People

- ❁ GPS Receivers



## Satellites

- 24 satellites
- 6 orbiting planes
- 55 degree inclination
- 20200 km above Earth
- 12 hours of orbit
- 5 hours view in horizon





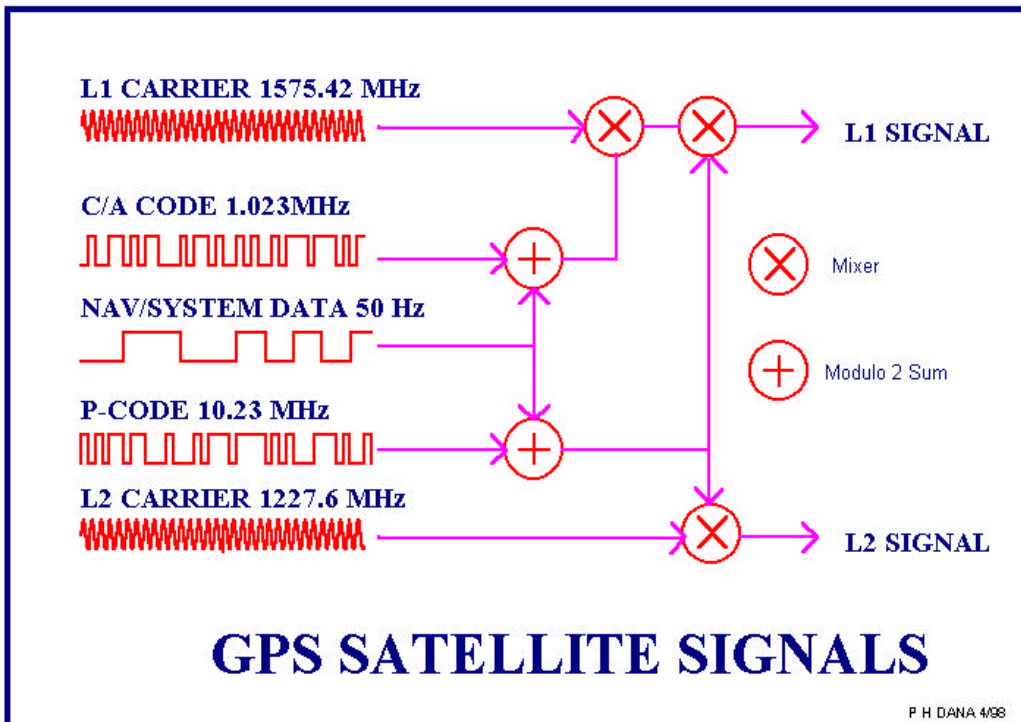
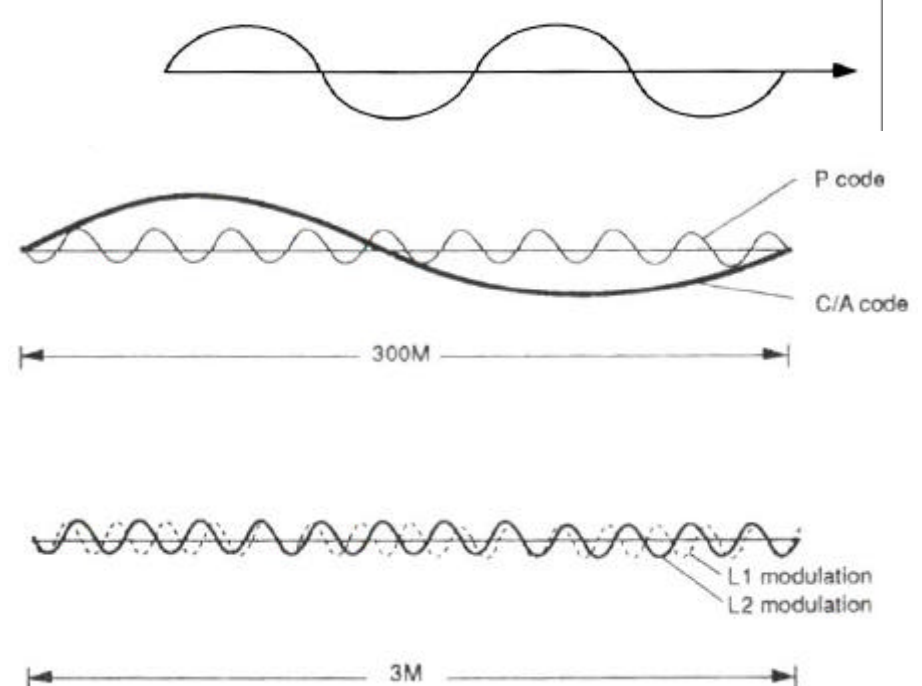
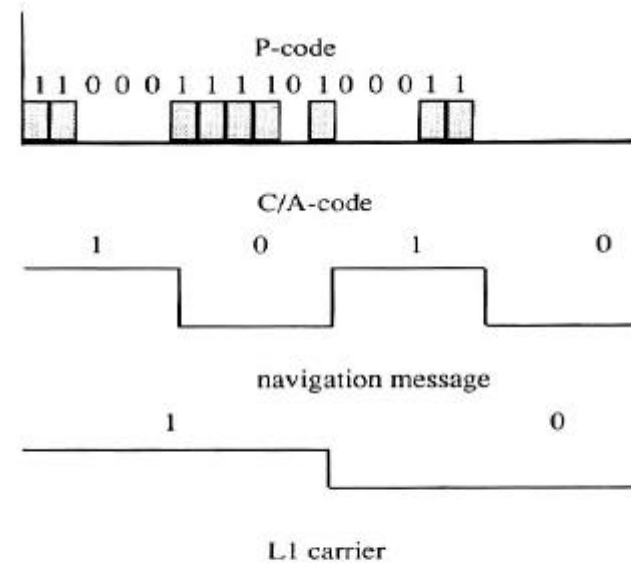
## Signals

**L1 carrier (154\*10.23 MHz)**  
 P code + C/A code + data message

$$l_{L1} = 19.05 \text{ cm}$$

**L2 carrier (120\*10.23 MHz)**  
 P code + data message

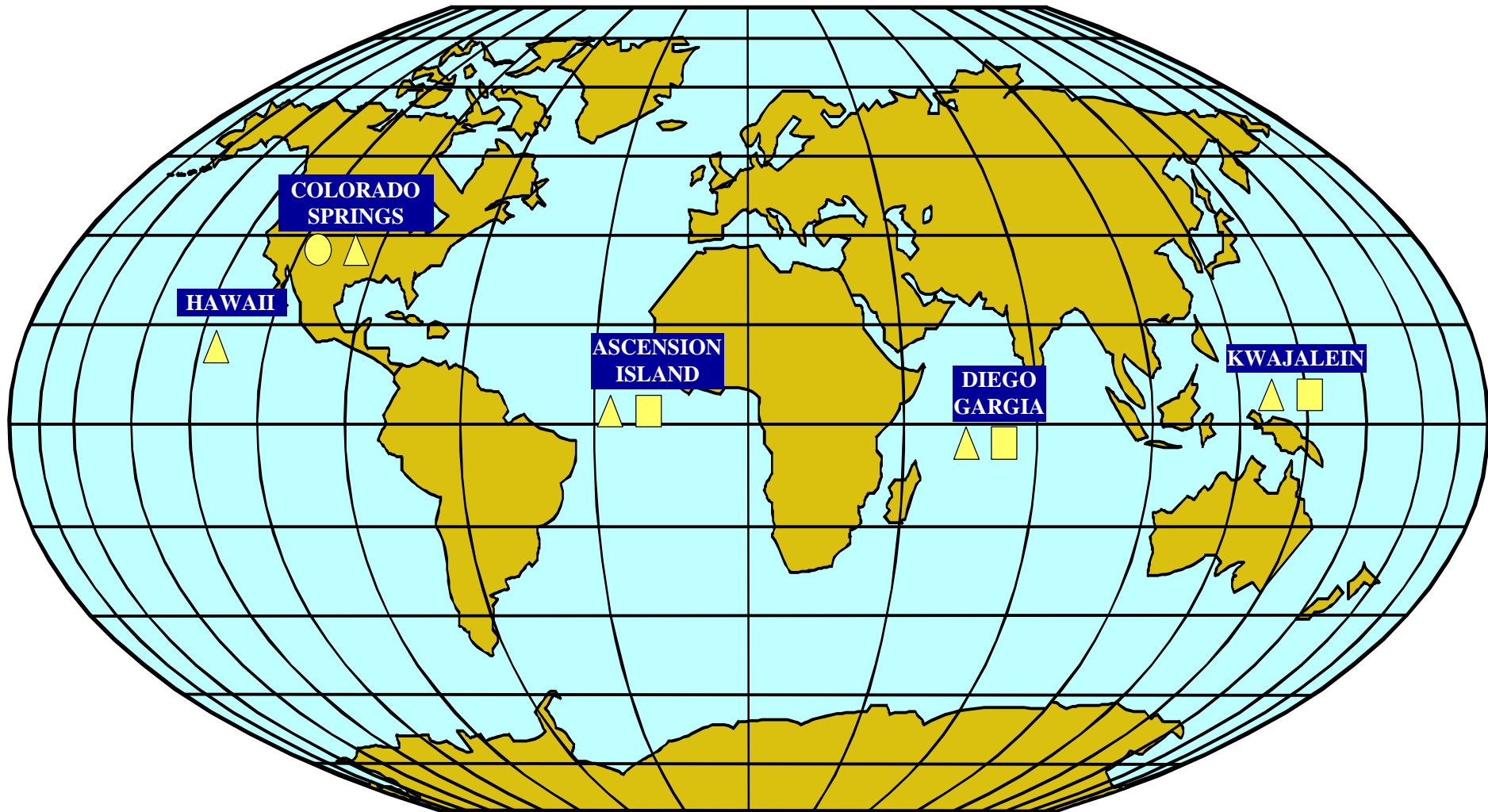
$$l_{L2} = 24.45 \text{ cm}$$



## GPS SATELLITE SIGNALS

P H DANA 4/98

## Distribution



( by M. Sahin )



## User Segment

### User Community

Civilian

Military

### Receiver

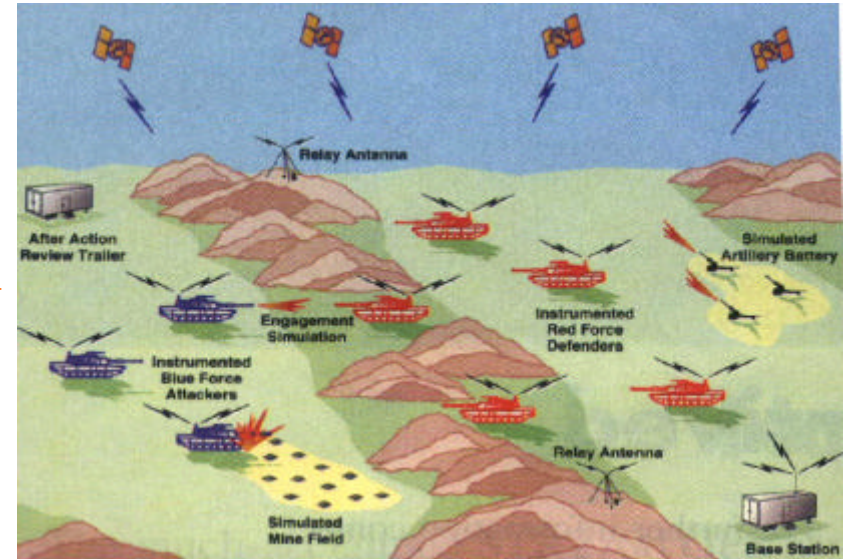
Trimble

Ashtech

Rogue

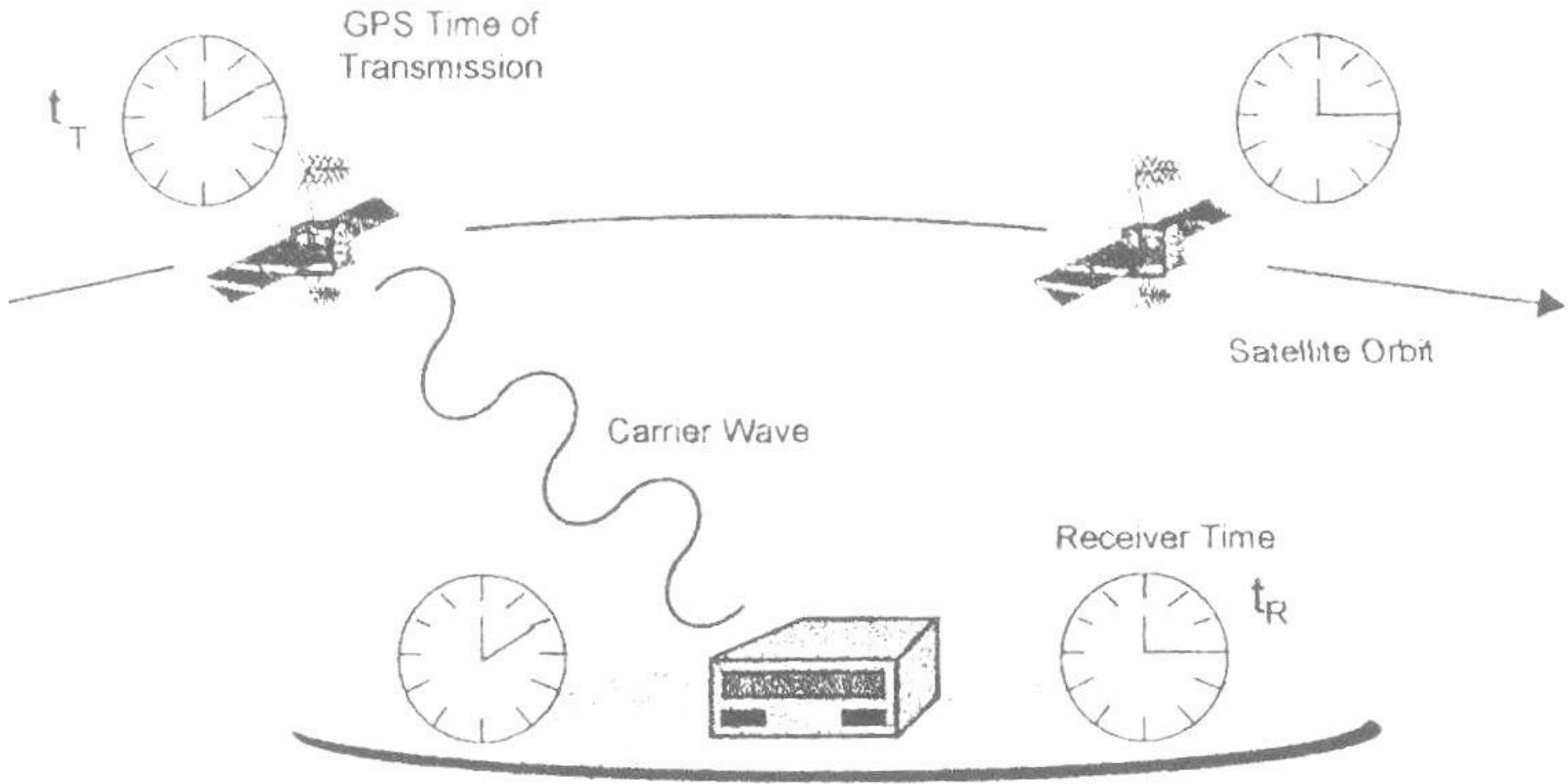
Leica

Javad ...



- **Code PseudoRange**
  - P and C/A codes.
- **Carrier Phase PseudoRange**
  - Phases of L1 and L2 carrier signals
  - Single-Difference, Double-Difference ...

Codes PseudoRange



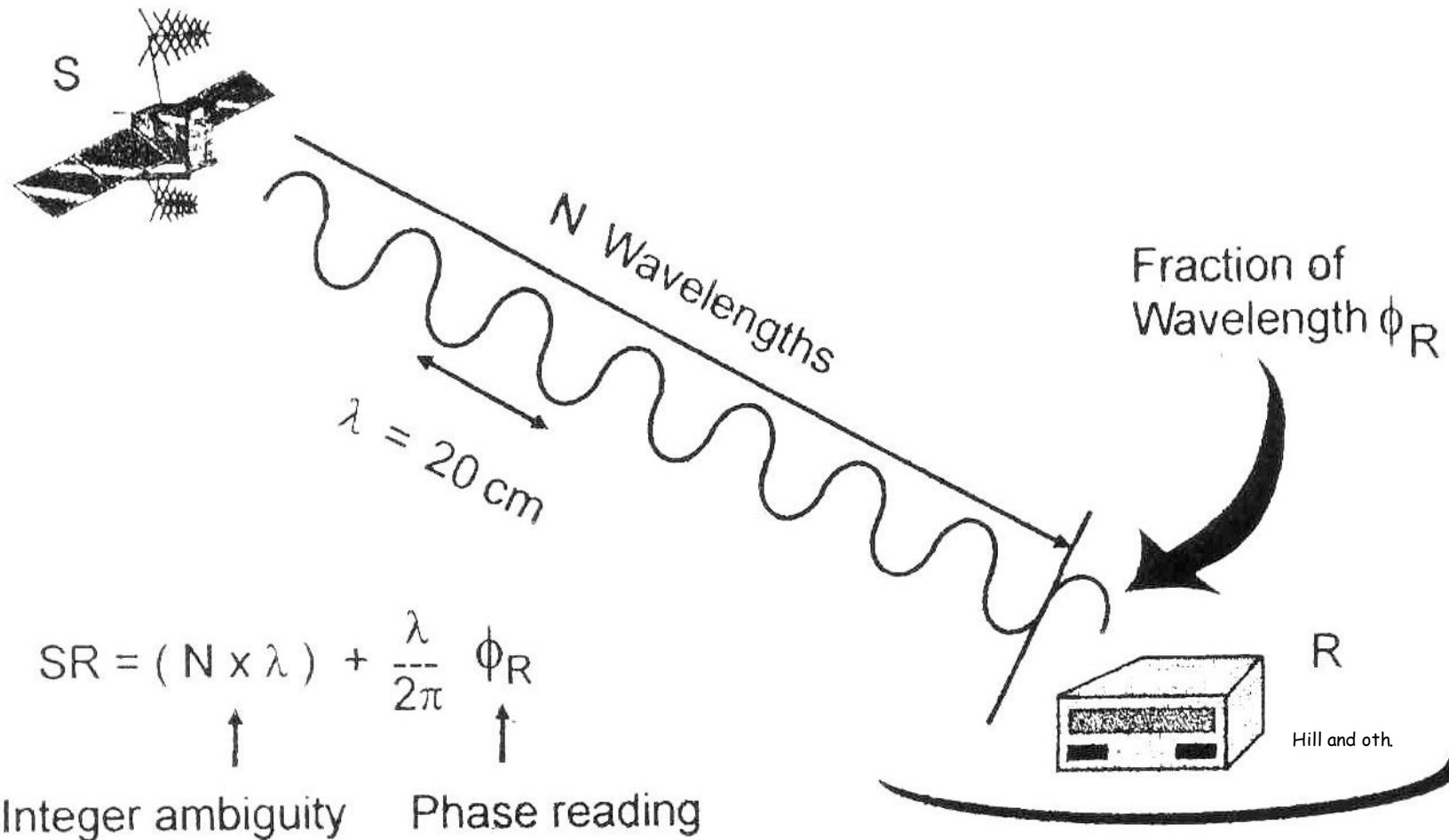
$$\text{(Pseudo-) Range} = t_R - t_T$$

Hill and oth.



Carrier Phases PseudoRange

- Phases of L1 and L2 carrier signals
  - L3, L4, L5



## Carrier Phase Observations

$$f_A^k(t) = -\frac{f}{c} r_A^k(t) + N_A^k + f^k(t) - f_A(t) + \textit{other errors}$$

Where,  $f_A^k$  : phase measured at A for k at time t

$r_A^k$  : geometric range from A to k

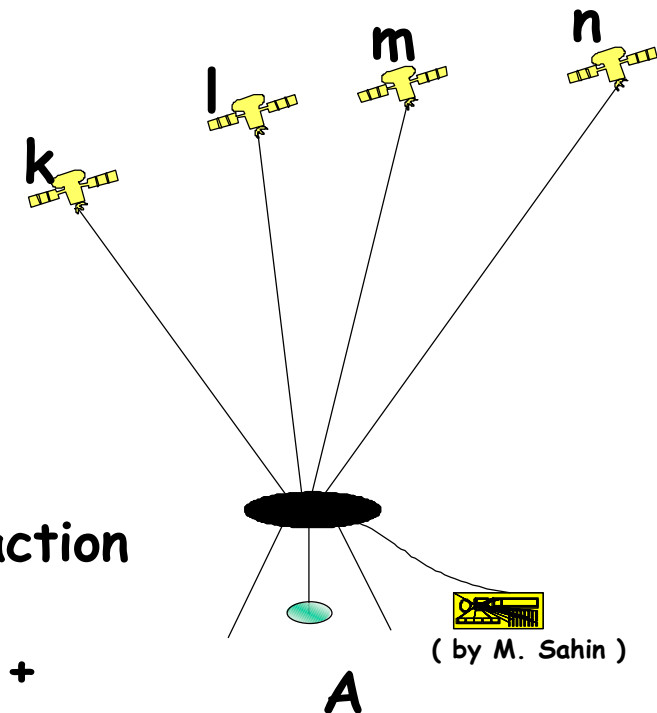
$N_A^k$  : initial unknown integer number of cycles between k & A

$f^k$  : Satellite clock error

$f_A$  : Receiver clock error

$f$  : frequency of signal

$c$  : speed of light



## Other errors

= Tropospheric refraction + ionospheric refraction  
 + noise & biases + multipathing effects  
 + antenna phase center offset & variation +  
 etc..

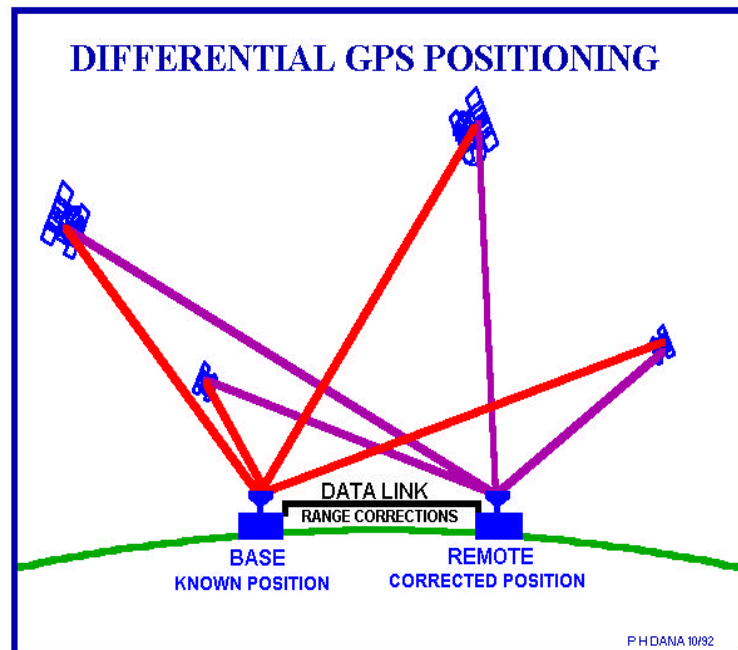
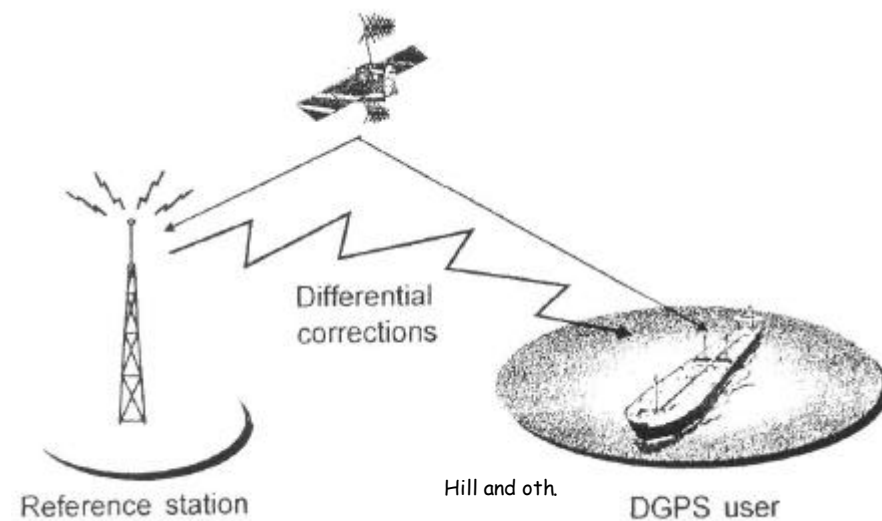


Codes PseudoRange

## Differential GPS

Diferential Code

Diferential Carrier



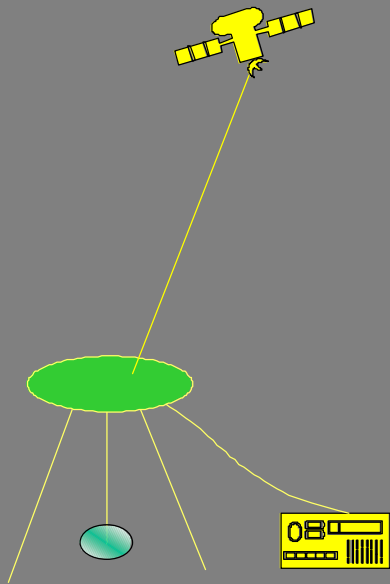
## GPS ERROR SOURCES

ERROR SOURCE	TYPICAL RANGE ERROR	DGPS (CODE) RANGE ERROR <100 KM REF-REMOTE
SV CLOCK	1 M	
SV EPHEMERIS	1 M	
SELECTIVE AVAILABILITY	10 M	
TROPOSPHERE	1 M	
IONOSPHERE	10 M	
PSEUDO-RANGE NOISE	1 M	1 M
RECEIVER NOISE	1 M	1 M
MULTIPATH	0.5 M	0.5 M
RMS ERROR	15 M	1.6 M
ERROR * PDOP=4	60 M	6 M

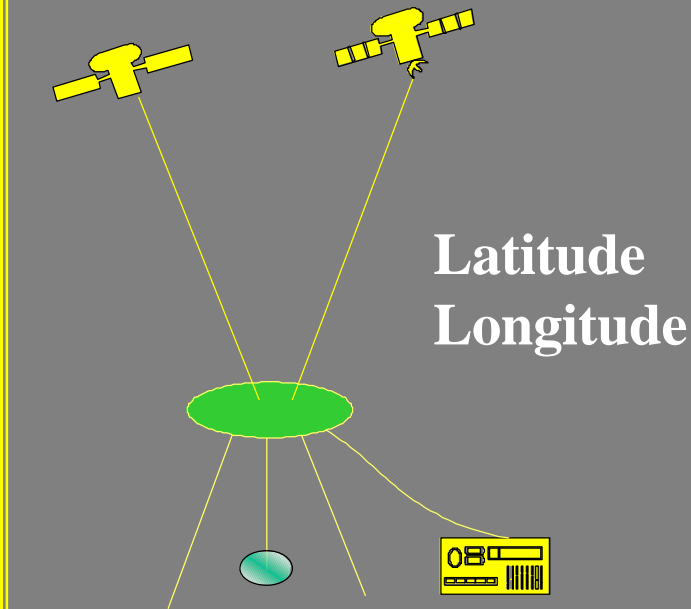
PDOP=Position Dilution of Precision (3-D) 4.0 is typical

## Satellite Positioning

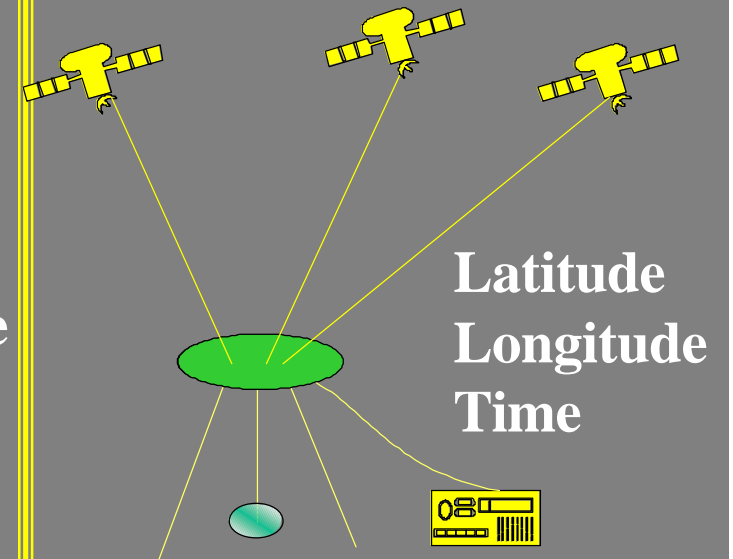
1 satellite



2 satellites



3 satellites

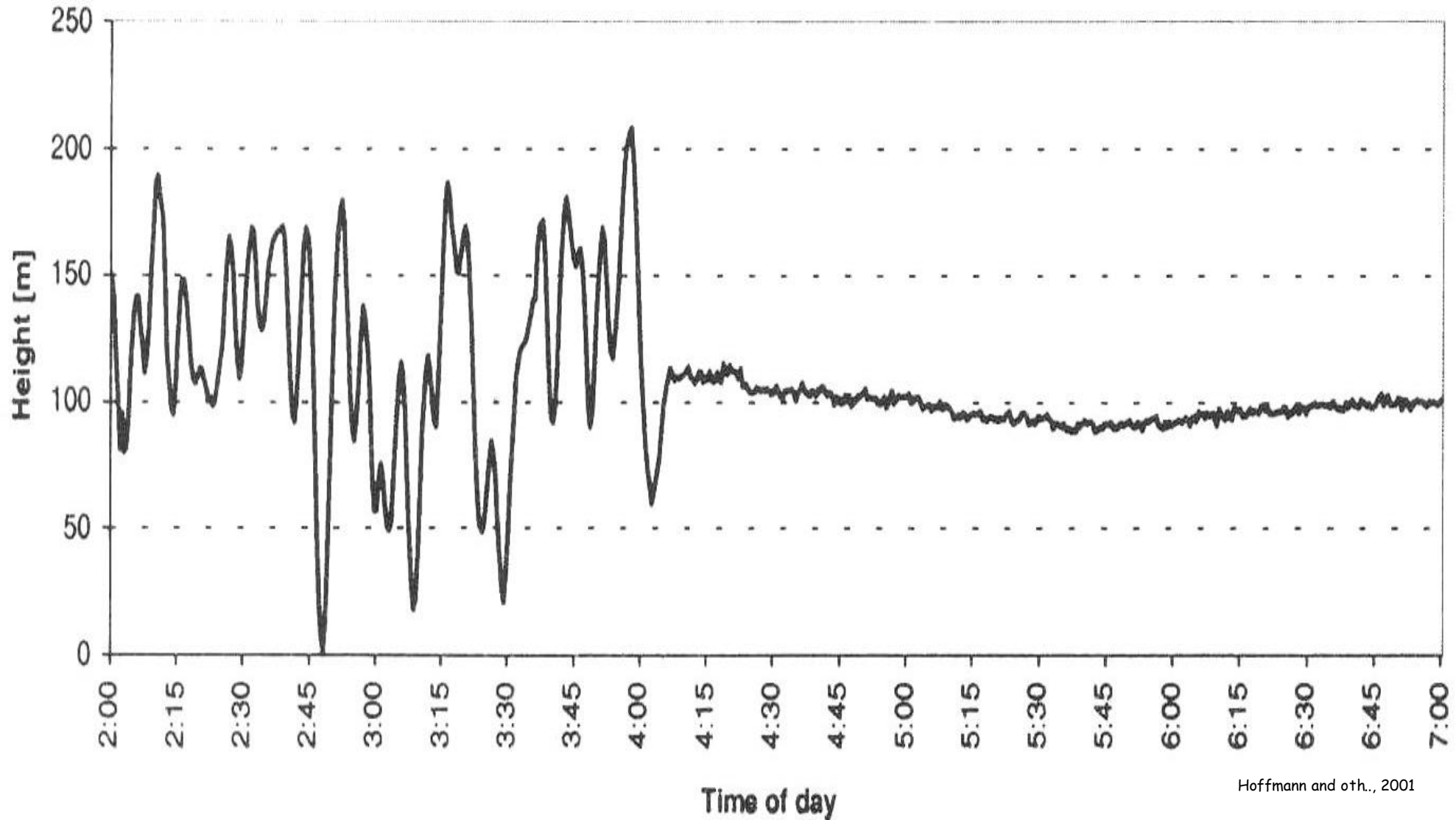


- **Absolute Positioning**
  - Navigation, Code Observation
- **Diferential Positioning**
- **Relative Positioning**
  - Static Relative Positioning
  - Fast Static Relative Positioning
  - Kinematic Relative Positioning

Types

- **SELECTIVE AVAILABILITY (SA)**
- **GEOMETRIC DILUTION OF PRECISION (GDOP)**
- **IONOSPHERIC EFFECT**
- **TROPOSPHERIC EFFECT**
- **OTHER EFFECTS**

## Selective Availability



HEIGHT VARIATION IN THE STATION KOOTWIJK (NEDERLANDS)  
DURING THE SA TRANSITION ON MAY 2, 2000

## GDOP

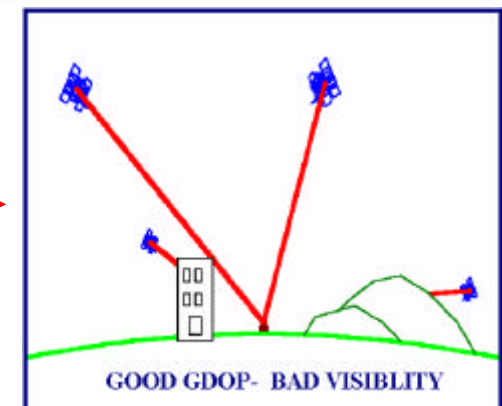
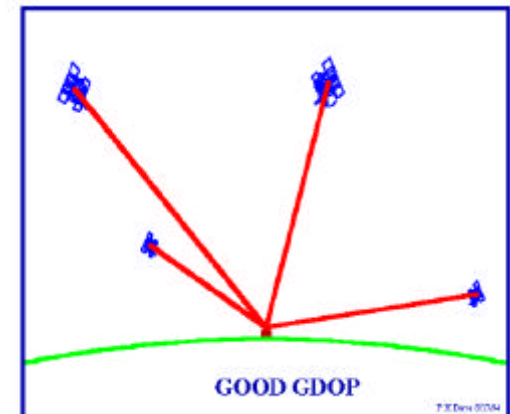
## GEOMETRIC DILUTION OF PRECISION (GDOP)

- Range vector differences between the receiver and the SVs

- Poor GDOP
- Good GDOP
- Good Computed GDOP and Bad Visibility

### •GDOP Components

- PDOP : Position Dilution of Precision (3-D), sometimes the Spherical DOP.
- HDOP : Horizontal Dilution of Precision (Latitude, Longitude).
- VDOP : Vertical Dilution of Precision (Height).
- TDOP : Time Dilution of Precision (Time).



#### ⇒ IONOSPHERIC EFFECT

⇒ 50-500 Km.

⇒ Delay: 10 meters.

#### ⇒ TROPOSPHERIC EFFECT

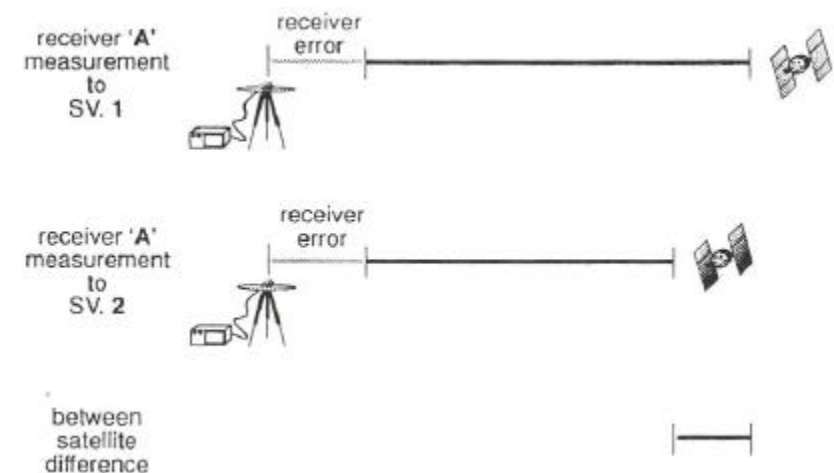
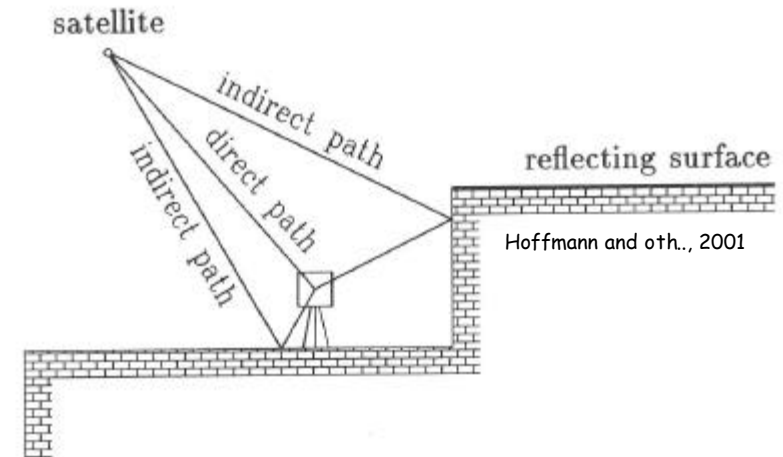
⇒ 8-13 Km.

⇒ Delay: 1 meter.



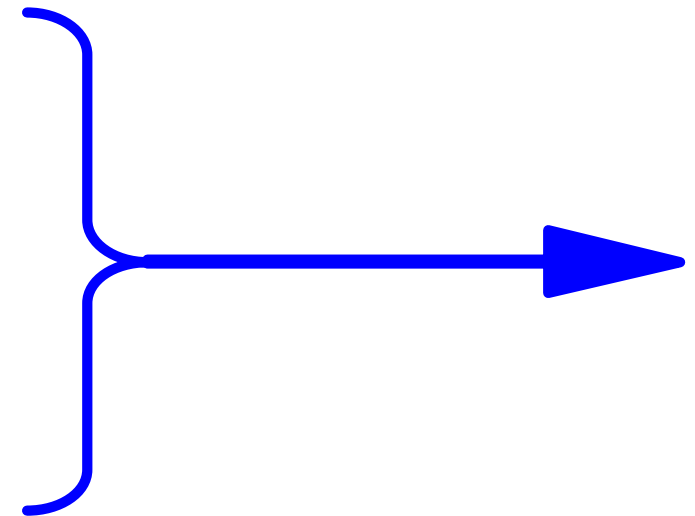
- SV clock errors
- Ephemeris data errors
- Multipath (Ghost)
- Control segment mistakes
- User mistakes
- Receiver errors
- Noise and bias errors

## Others



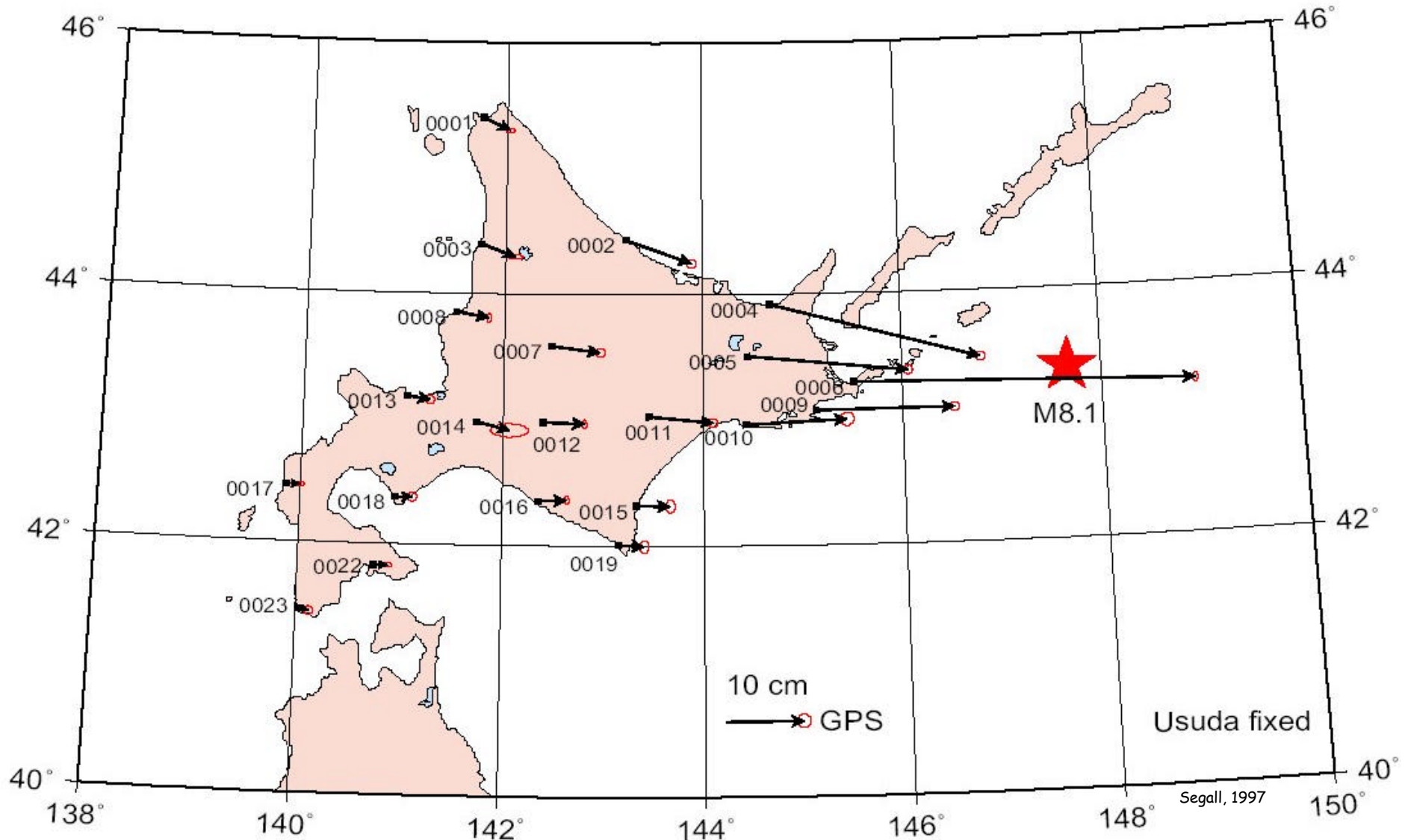
### ➤ **GEOPHYSICS USES GPS TO EXPLAIN**

- Plate Movement and Plate Boundary Deformations
- Volcanic Deformation
- Glacial Isostatic Adjustment and Sea Level Change
- Landslide and Dam Deformations
- **Earthquake Studies**
  - **Interseismic Deformation**
  - **Coseismic Deformation**
  - **Postseismic Deformation**



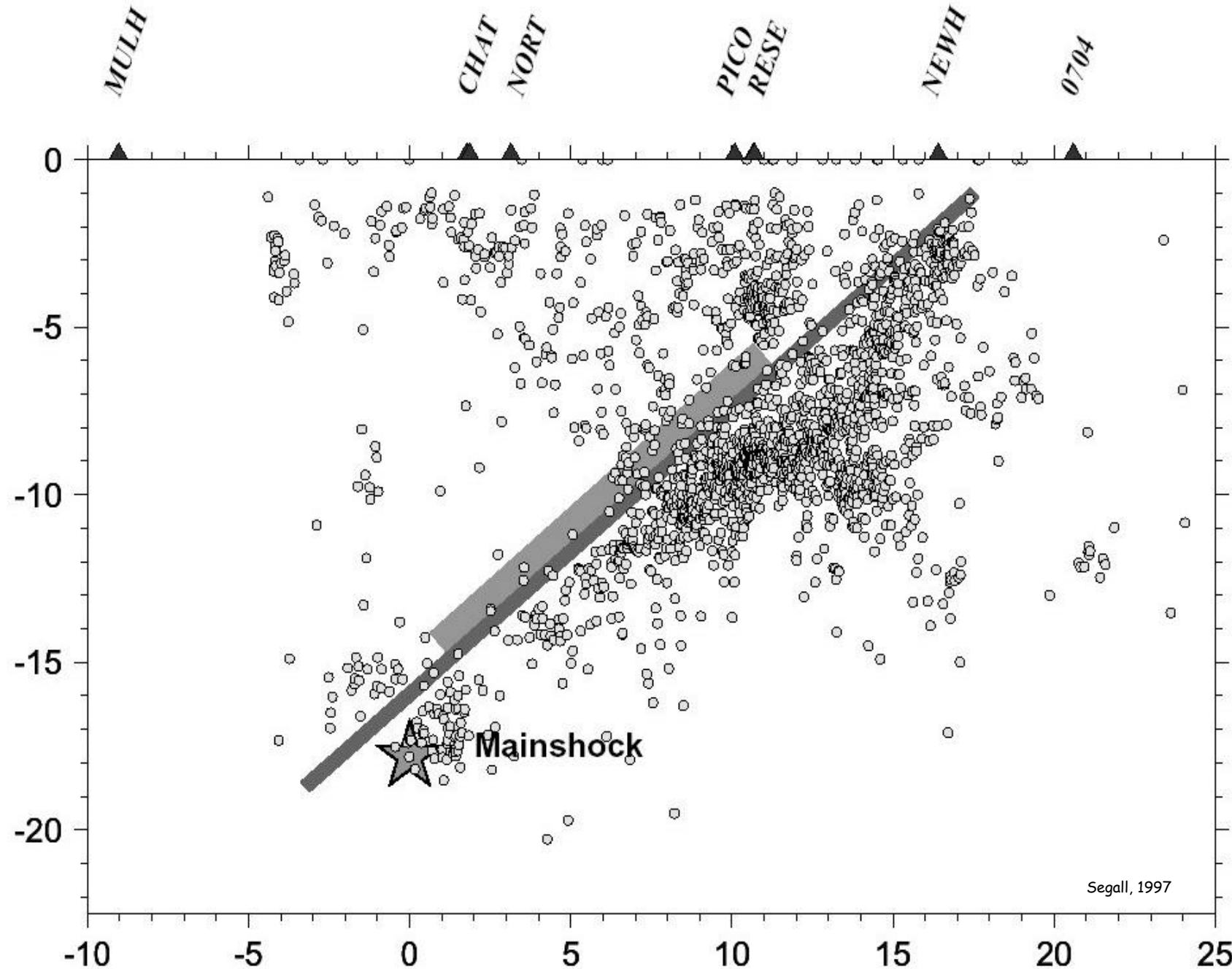
### Earthquake Studies Coseismic Deformation

#### M8.1 Kurile Island, Hokkaido-Toho-Oki, Japan, Earthquake, 1994.



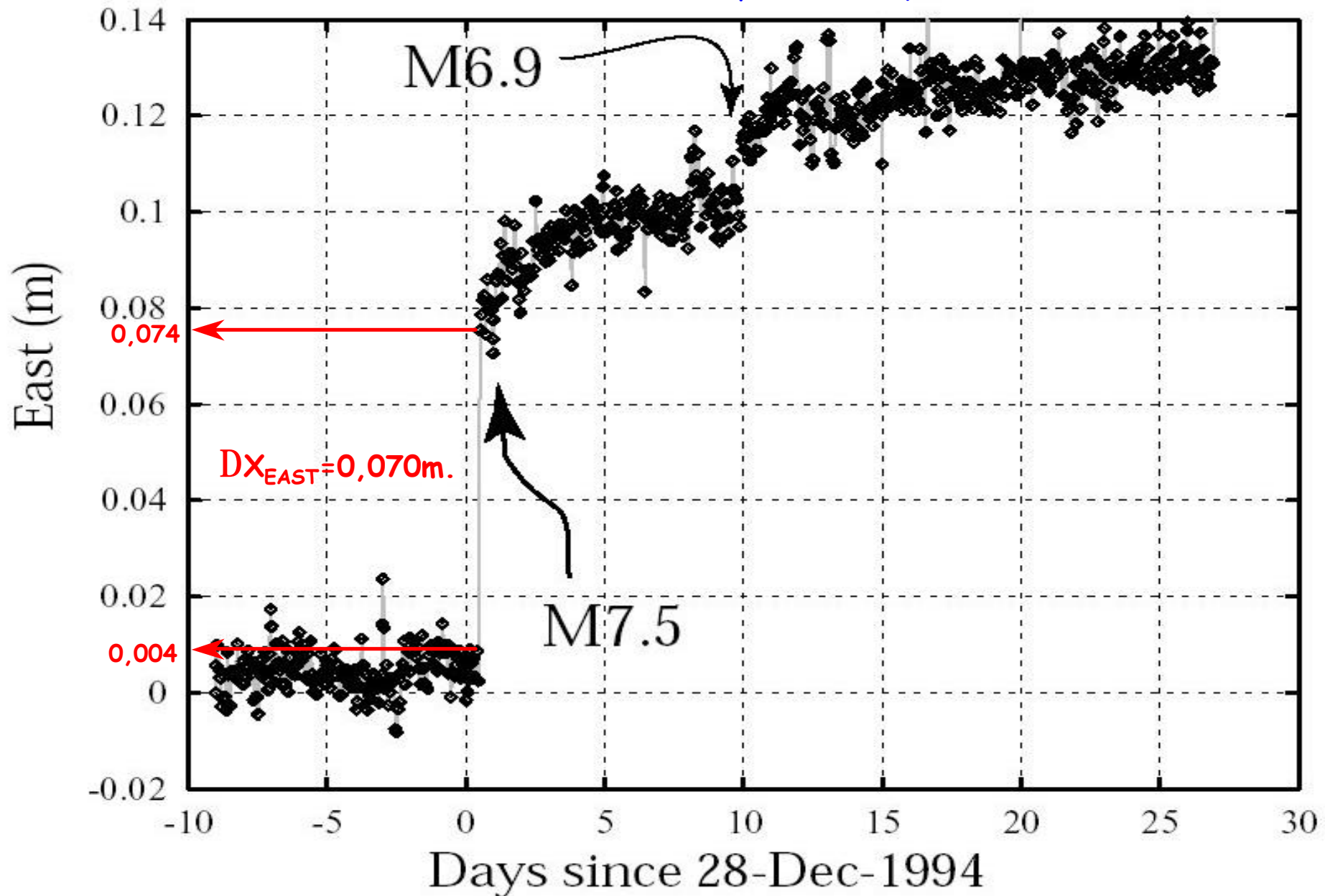
M6.7 Nothridge, 1994

Earthquake Studies Coseismic Deformation



### Earthquake Studies Postseismic Deformation

M7.5 Sanriku Haruka Oki, Japan, Earthquake, 1994



- Many of interseismic studies is in southern California
- Northridge Earthquake
  - Donnellan, 1993,  $M \sim 6.4$  → 1994,  $M 6.7$
- Bennett ve oth. (1996), Donnellan and oth. (1993), Feigl and oth. (1993)



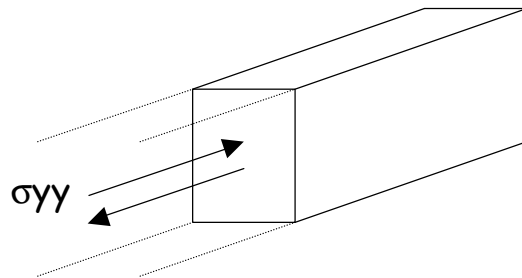
### Earthquake Studies Modeling of GPS Data for Geophysical Studies

Point  
Coordinate

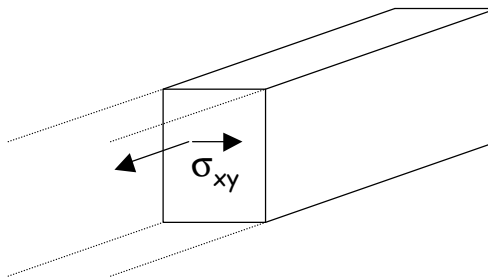
Measurement  
Style  
Duration

Vectorial  
Coordinate

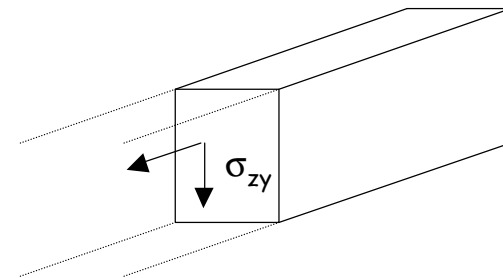
There are three mod of a substance are exposed to dislocation



1. mod deformation.



2. mod deformation.

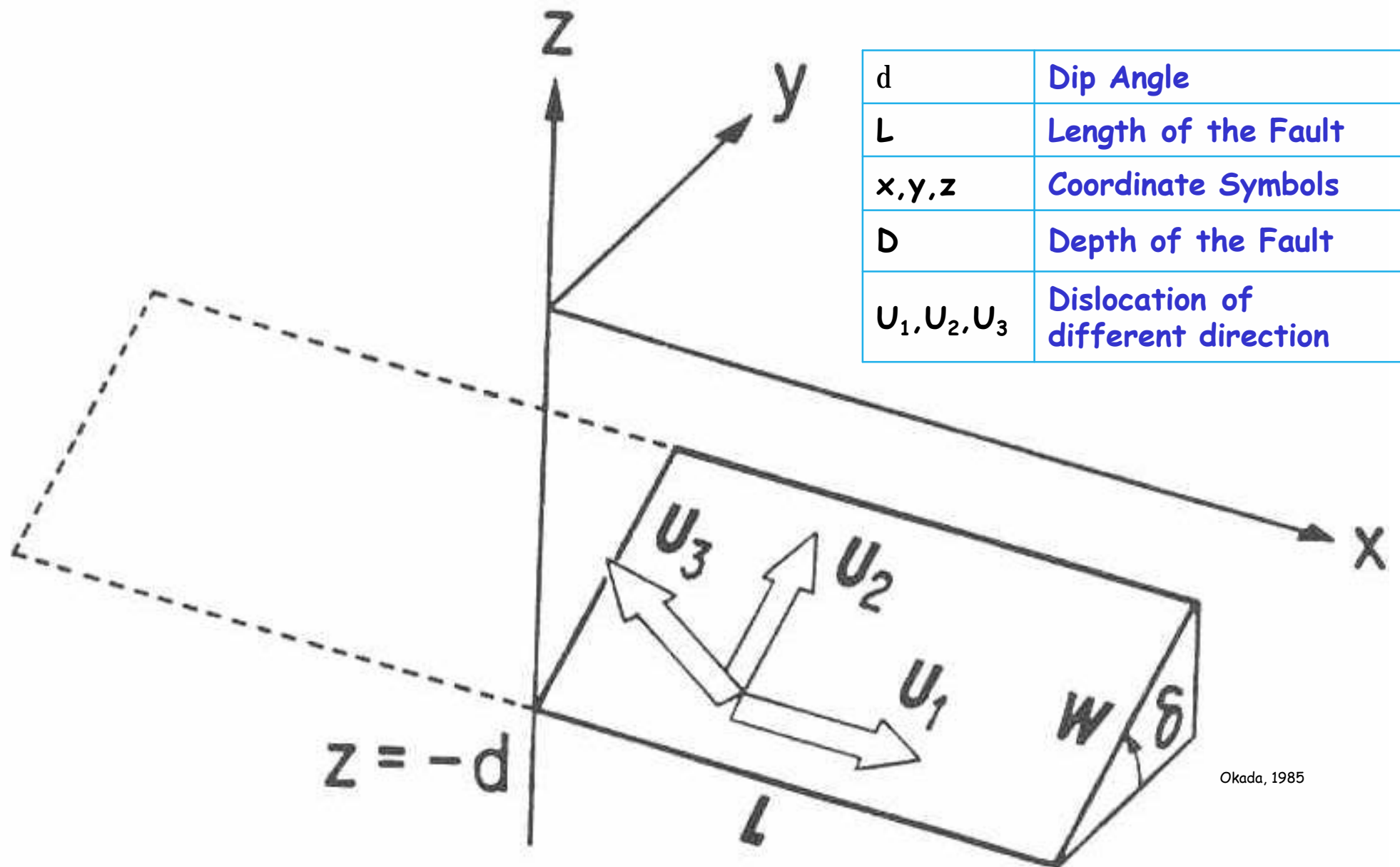


3. mod deformation.



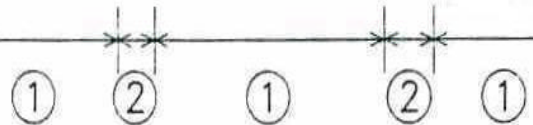
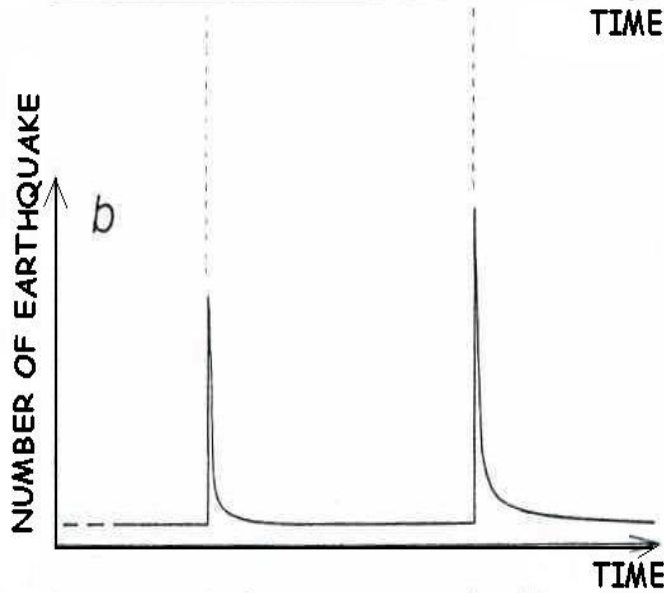
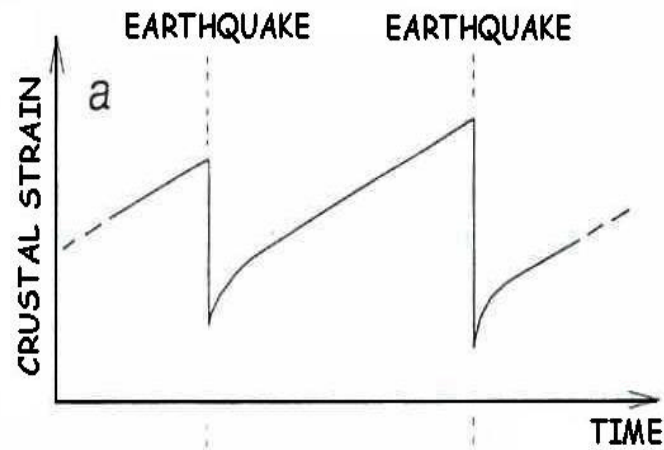
### Earthquake Studies

### Effects of the Source Geometry on Dislocation Area

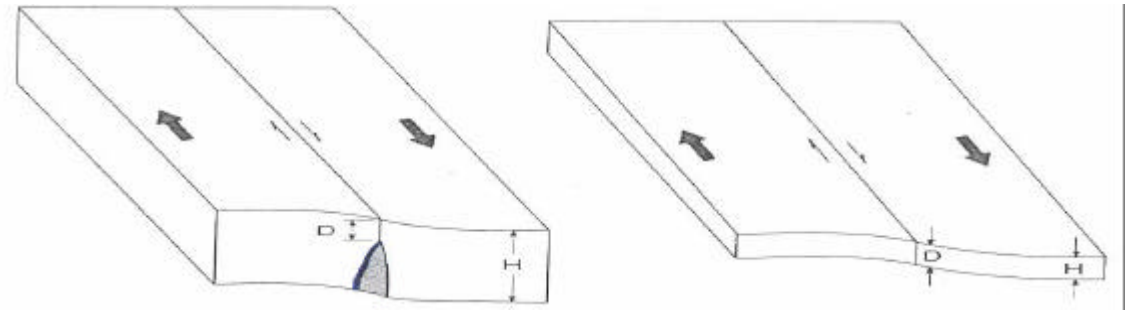


Okada, 1985

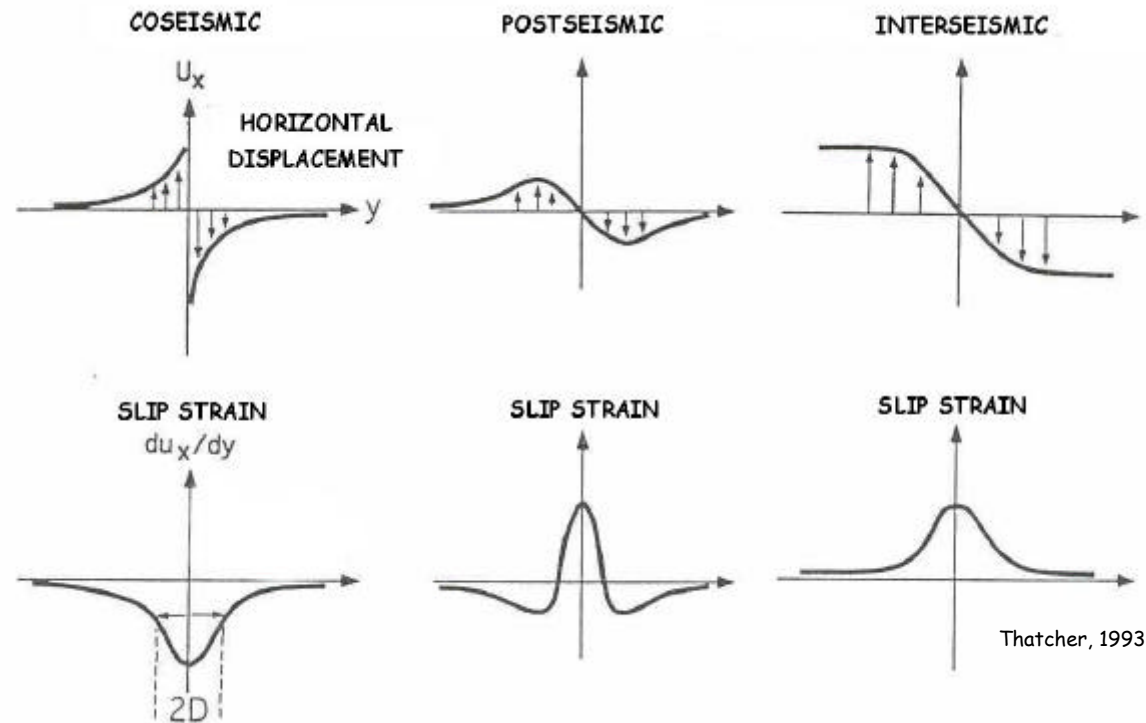
## Deformation Cycle of Earthquake and Strain Relation



Thatcher, 1993

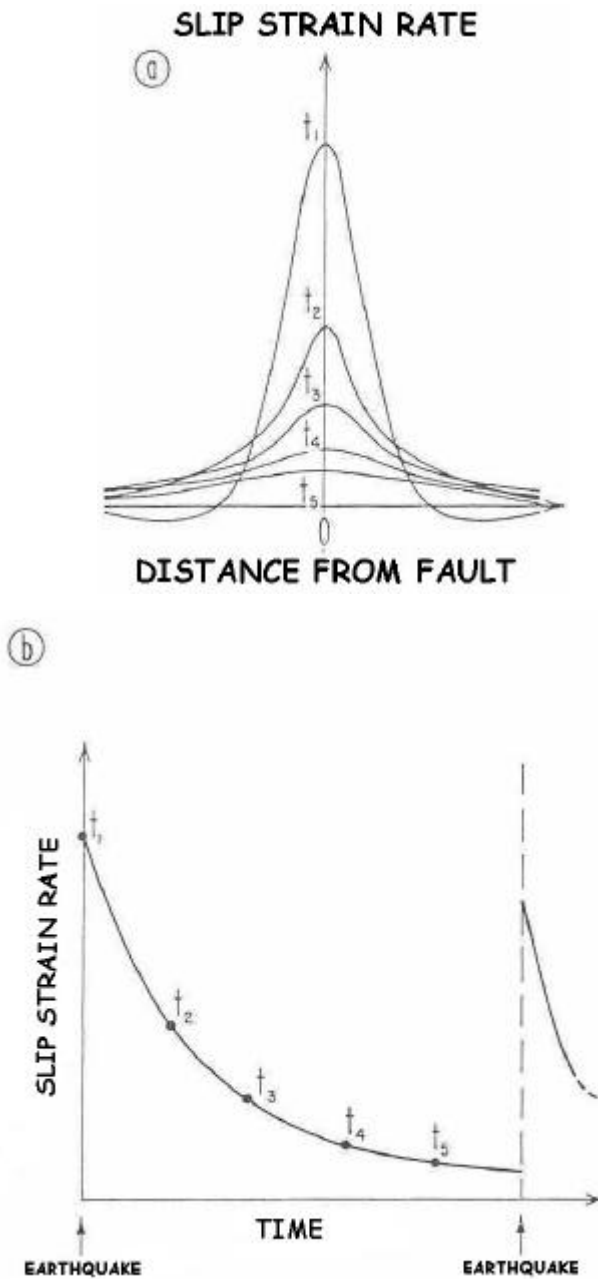


Thatcher, 1993

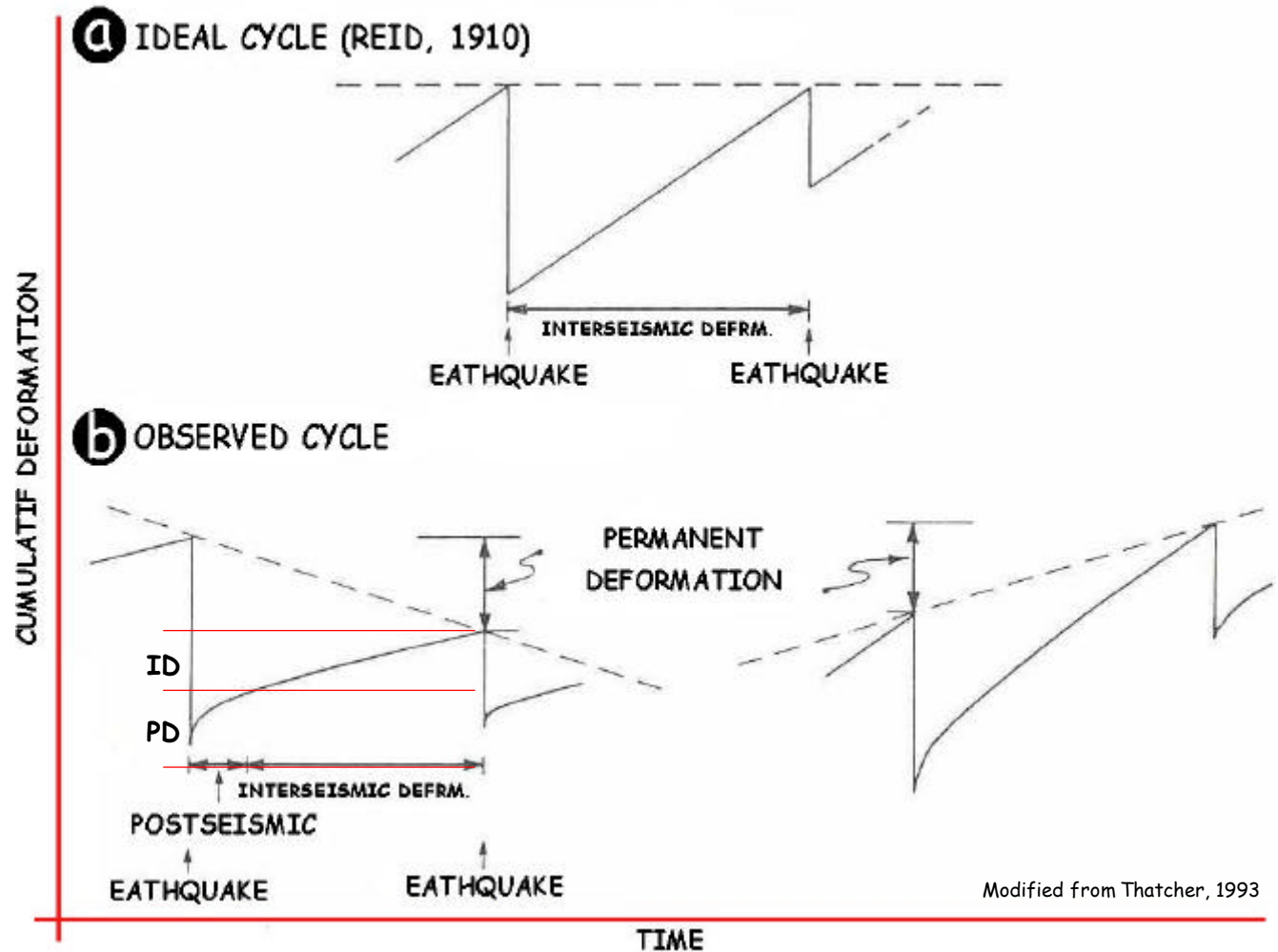


Thatcher, 1993

## Deformation Cycle of Earthquake and Strain Relation

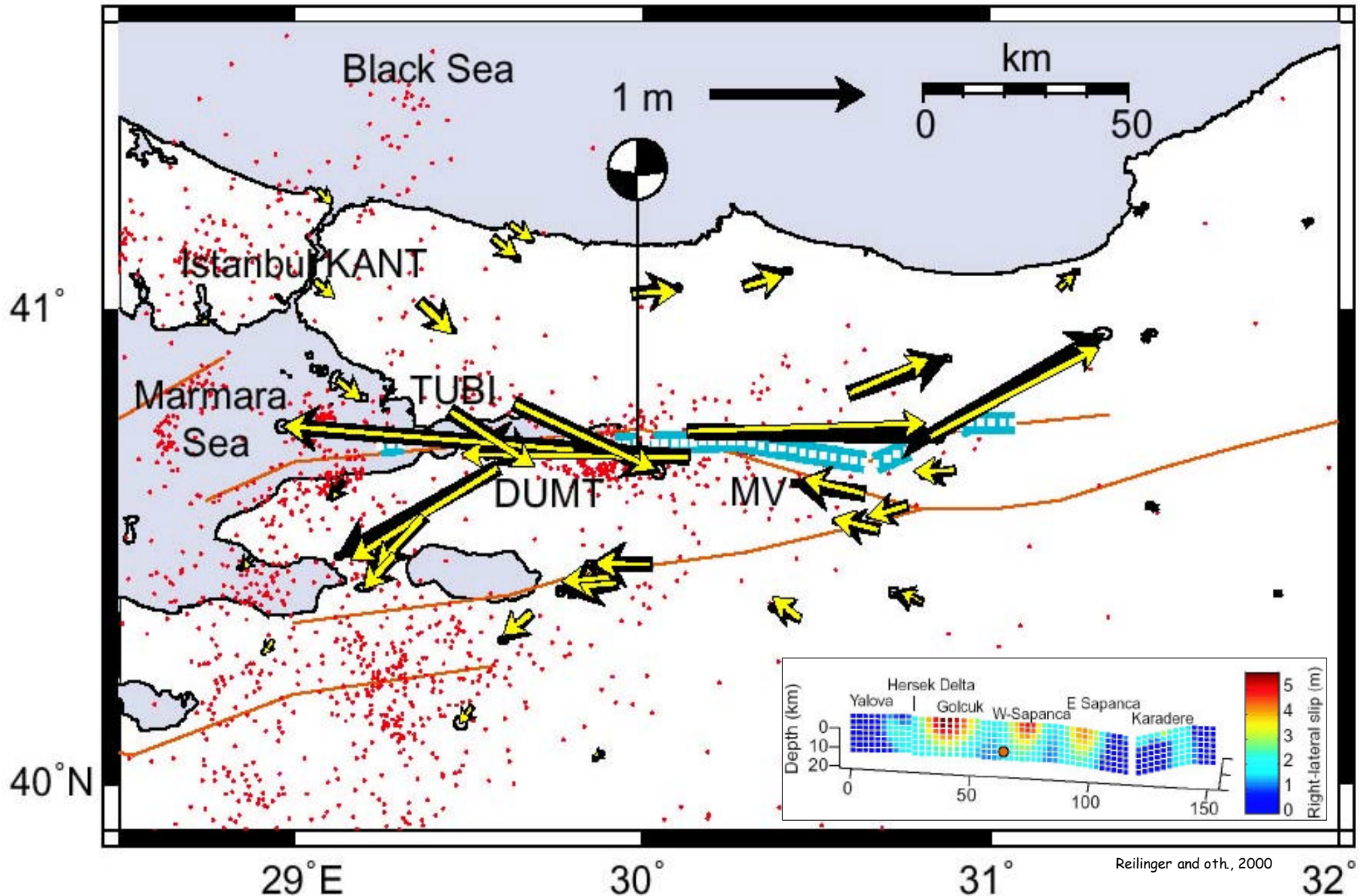


Thatcher, 1993



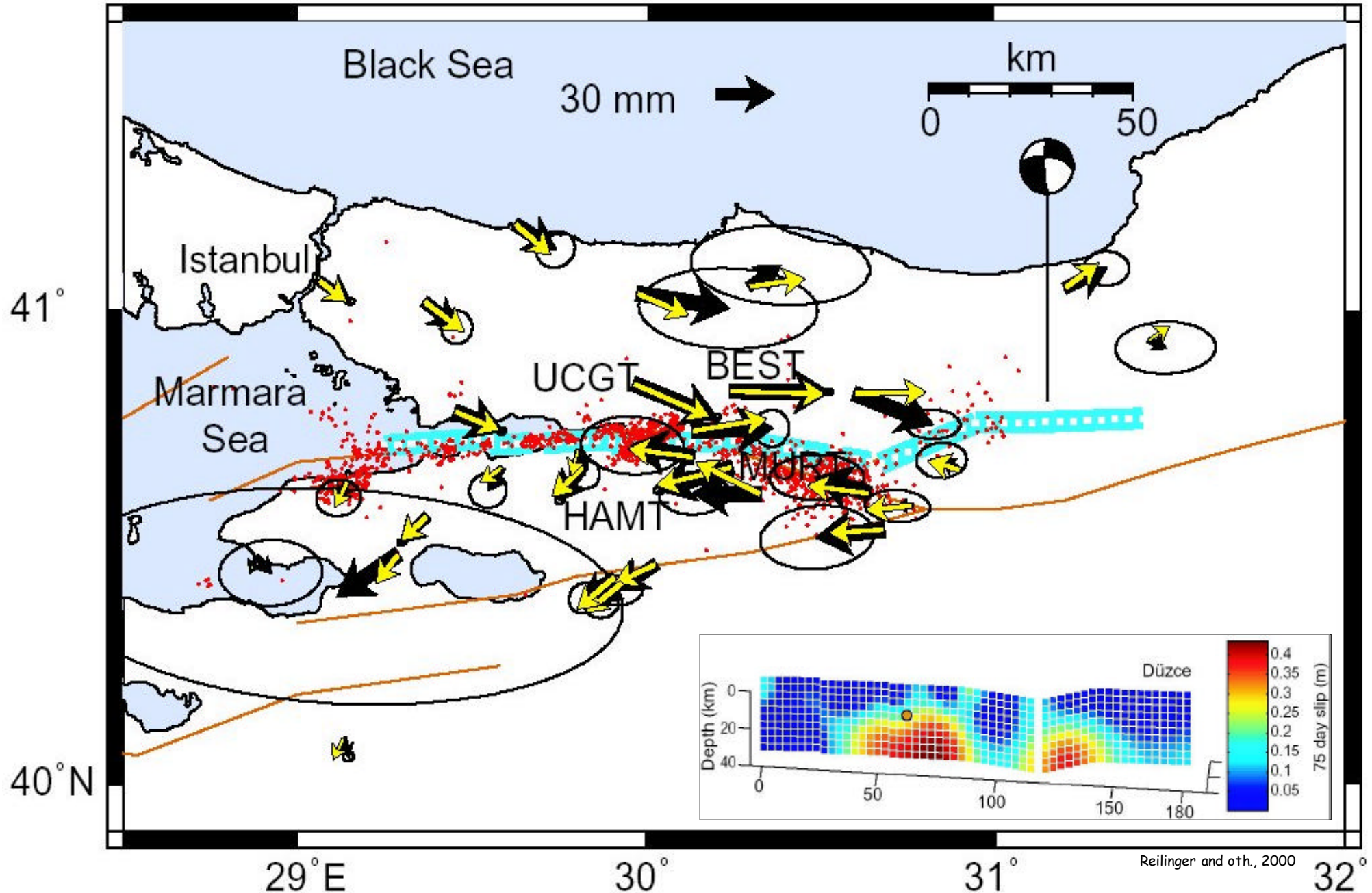
Modified from Thatcher, 1993

## Examples of GPS Studies for 1999, Kocaeli Earthquake



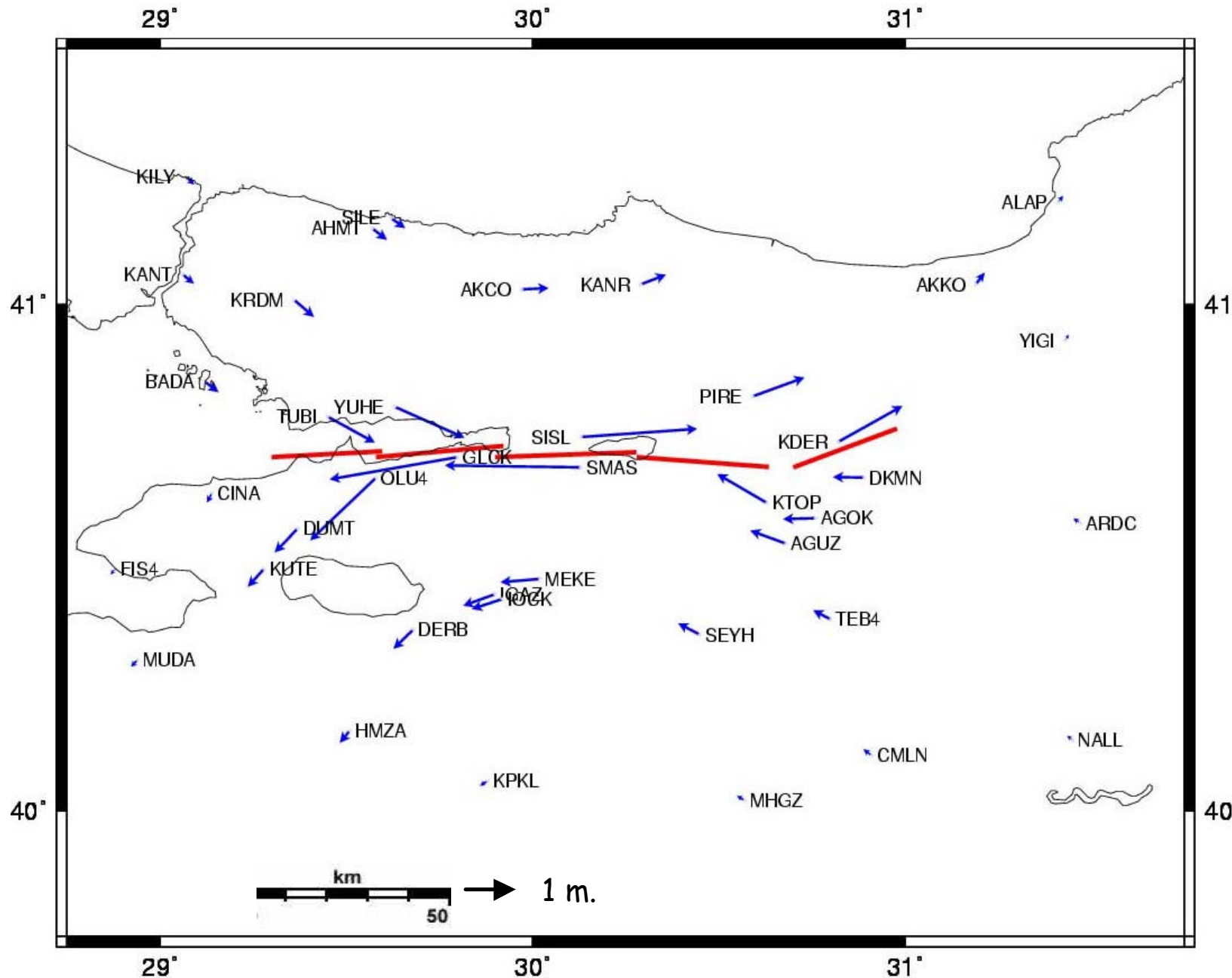


### Examples of GPS Studies for Kocaeli Earthquake



- Modeling Program
  - uses Okada's definitions
  - was written by Semih Ergintav and oth.
    - (TUBITAK-MRC-EMSRI).
  - reads the data from a file
  - calculates displacements at two dimension for every defined point.
- Then, saved data is given to GMT as input file. GMT plot the data on a map.

### Examples of Modelling Program



Şekil No	1. Frey	2. Frey	3. Frey	4. Frey	5. Frey
Enlem (°)	40.7	40.7	40.7	40.7	40.68
Boylam (°)	29.3	29.58	29.9	30.28	30.7
Şerhler (°)	87	85	88	94	70
Derinlik (cm)	20.0	20.0	20.0	20.0	20.0
Eğim Açısı (°)	90.0	90.0	90.0	90.0	90.0
Uzunluk (cm)	2.5	2.9	3.2	3.0	2.5
Genişlik (cm)	20.0	20.0	20.0	20.0	20.0
x Yönlünde Atım (cm)	-100	-570	-550	-400	-300
y Yönlünde Atım (cm)	0.0	0.0	0.0	0.0	0.0



### RESULTS and SUGGESTIONS

- ✓ Precise and economic method
- ✓ Geophysics
  - ✓ earthquake studies and deformation analysis
    - ✓ Interseismic deformation
    - ✓ Postseismic deformation
    - ✓ coseismic deformation
- ✓ Kocaeli Earthquake
- ✓ a computer program
- ✓ MAGNET

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<http://schubert.ign.fr/CIAG/WITRF/ITRF-GPS.html>

<http://wings.buffalo.edu/academic/department/som/students/clubs/KMBA/work/mgs/ywgps/gps.html>

[http://www.casdn.neu.edu/~geology/department/staff/colgan/class\\_notes/gis/1441-19.htm](http://www.casdn.neu.edu/~geology/department/staff/colgan/class_notes/gis/1441-19.htm)

[http://www.colorado.edu/geography/gcraft/notes/gps/gps\\_f.html](http://www.colorado.edu/geography/gcraft/notes/gps/gps_f.html)

[http://www.gmat.unsw.edu.au/snap/gps/gps\\_links.htm](http://www.gmat.unsw.edu.au/snap/gps/gps_links.htm)

<http://www.gpsworld.com/resource.htm>

[http://www.ifag.de/Geodaesie/earth\\_rotation/three.htm](http://www.ifag.de/Geodaesie/earth_rotation/three.htm)

<http://www.navcen.uscg.mil/gps/>

<http://www.navtechgps.com/supply/books.asp?Line=basic>

<http://www.ngs.noaa.gov/>

<http://www.nima.mil/GandG/tr.html>

[http://www.osg.vic.gov.au/sbv\\_gps/SURVGPS.html](http://www.osg.vic.gov.au/sbv_gps/SURVGPS.html)

<http://www.sonic.net/~trollhei/survsoft.html>

[http://www.udel.edu/johnmack/frec480/gps\\_intro.htm](http://www.udel.edu/johnmack/frec480/gps_intro.htm)

<http://www.unb.ca/gge/HotList.html>

<http://www2.geod.nrcan.gc.ca/~craymer/tcg/tcg.html#list>

<http://www2.una.edu/geography/classes/ge424/gps1/>

# Global Positioning System

Presentation can be procured from the Web Address:

<http://kandilli-gp.tripod.com>

Thank you for your interest

**Dogan AKSARI**

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